

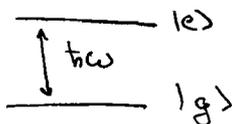
# CVIČENÍ

①

operátor hustoty  $\hat{\rho} = \sum_i p_i |\psi_i\rangle \langle \psi_i|$

$$\langle \hat{A} \rangle = \text{Tr}(\hat{\rho} \hat{A})$$

$$\frac{d\hat{\rho}}{dt} = \frac{1}{i\hbar} [\hat{H}, \hat{\rho}]$$



① spontánní emise

②  $|\psi(t)\rangle = \alpha |e\rangle \otimes |n\rangle + \delta |g\rangle \otimes |n+1\rangle$

$$|\psi_A(t=0)\rangle = |e\rangle, |\psi_{EN}(t=0)\rangle = \frac{1}{\sqrt{2}} (|p\rangle + |p-1\rangle)$$

$$\Rightarrow |\psi(t)\rangle = \frac{1}{\sqrt{2}} \alpha |e\rangle \otimes (|p\rangle + |p-1\rangle) + \frac{1}{\sqrt{2}} \delta |g\rangle \otimes (|p\rangle + |p+1\rangle)$$

$|e\rangle|p\rangle$  a  $|g\rangle|p+1\rangle$   
 $|e\rangle|p-1\rangle$  a  $|g\rangle|p\rangle$   
 mají (podvojících)  
 stejnou energii

③  $|e\rangle \otimes |p-1\rangle, |e\rangle \otimes |p\rangle, |e\rangle \otimes |p+1\rangle$   
 $|g\rangle \otimes |p-1\rangle, |g\rangle \otimes |p\rangle, |g\rangle \otimes |p+1\rangle$

④  $\hat{\rho} = \sum_i p_i |\psi_i\rangle \langle \psi_i|$

maticové elementy určíme  $\langle u_n | \hat{\rho} | u_p \rangle = \langle u_n | \psi \rangle \langle \psi | u_p \rangle$ , kde  $|u_n\rangle, |u_p\rangle$  jsou naše <sup>bazové</sup> stavy

$$\begin{aligned} \rightarrow \text{napr. } \langle e | \langle p-1 | \hat{\rho} | e \rangle | p-1 \rangle &= \langle e | \langle p-1 | \left[ \frac{1}{\sqrt{2}} \alpha |e\rangle (|p\rangle + |p-1\rangle) + \frac{1}{\sqrt{2}} \delta |g\rangle (|p\rangle + |p+1\rangle) \right] \times \\ &\times \left[ \frac{1}{\sqrt{2}} \alpha^* \langle e | ( \langle p | + \langle p-1 | ) + \frac{1}{\sqrt{2}} \delta^* \langle g | ( \langle p | + \langle p+1 | ) \right] |e\rangle | p-1 \rangle = \\ &= \frac{1}{\sqrt{2}} \alpha \langle e | e \rangle ( \langle p-1 | p \rangle + \langle p-1 | p-1 \rangle ) + \\ &+ \frac{1}{\sqrt{2}} \delta \langle e | g \rangle ( \langle p-1 | p \rangle + \langle p-1 | p+1 \rangle ) \times \\ &\times \left[ \frac{\alpha^*}{\sqrt{2}} \langle e | e \rangle ( \langle p | p-1 \rangle + \langle p-1 | p-1 \rangle ) + \right. \\ &\left. - \frac{1}{\sqrt{2}} \delta^* \langle g | e \rangle ( \langle p | p-1 \rangle - \langle p+1 | p-1 \rangle ) \right] = \end{aligned}$$

= bazové fce jsou ortogonální a normalizované na 1 (tj. ortonormální)

$$\langle e | e \rangle = \langle g | g \rangle = 1 \quad \langle e | g \rangle = \langle g | e \rangle = 0$$

$$\langle p | p \rangle = 1 \quad \langle p+1 | p \rangle = 0$$

$$= \frac{1}{\sqrt{2}} \cdot \frac{\alpha^*}{\sqrt{2}} = \frac{1}{2} \alpha \alpha^*$$

a zcela analogicky pro zbylé členy  
 (+ můžeme využít symetrie)

②

$$\Rightarrow \rho = \frac{1}{2} \begin{pmatrix} \alpha\alpha^* & \alpha\alpha^* & 0 & 0 & \alpha\delta^* & \alpha\delta^* \\ \alpha\alpha^* & \alpha\alpha^* & 0 & 0 & \alpha\delta^* & \alpha\delta^* \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ \alpha^*\delta & \alpha^*\delta & 0 & 0 & \delta\delta^* & \delta\delta^* \\ \alpha^*\delta & \alpha^*\delta & 0 & 0 & \delta\delta^* & \delta\delta^* \end{pmatrix}$$

⑤ redukovaná matice hustoty

$$\langle \psi_A | \hat{\rho} | \psi_A \rangle = \sum_i \langle \psi_{A_i} | \psi_{\text{ent},i} | \hat{\rho} | \psi_{A_i} | \psi_{\text{ent},i} \rangle \equiv \rho_A$$

$$\begin{aligned} \langle e | \hat{\rho}_A | e \rangle &= \langle e | \langle p-1 | \hat{\rho} | e \rangle | p-1 \rangle + \langle e | \langle p | \hat{\rho} | e \rangle | p \rangle + \langle e | \langle p+1 | \hat{\rho} | e \rangle | p+1 \rangle = \\ &= \frac{1}{2} \alpha\alpha^* + \frac{1}{2} \alpha\alpha^* + 0 = \\ &= \underline{\underline{\alpha\alpha^*}} \end{aligned}$$

a analogicky  $\langle e | \hat{\rho}_A | g \rangle = \underline{\underline{\frac{1}{2} \alpha\delta^*}}$   
 $\langle g | \hat{\rho}_A | e \rangle = (\langle e | \hat{\rho}_A | g \rangle)^* = \underline{\underline{\frac{1}{2} \alpha\delta^*}}$   
 $\langle g | \hat{\rho}_A | g \rangle = \underline{\underline{\delta\delta^*}}$

$$\Rightarrow \underline{\underline{\rho_A = \begin{pmatrix} \alpha\alpha^* & \frac{1}{2} \alpha\delta^* \\ \frac{1}{2} \alpha\delta^* & \delta\delta^* \end{pmatrix}}}$$

⑥ čistý stav? tj.  $\text{Tr} \rho_A^2 = 1$ ?

$$\rho_A^2 = \begin{pmatrix} \alpha\alpha^* & \frac{1}{2} \alpha\delta^* \\ \frac{1}{2} \alpha\delta^* & \delta\delta^* \end{pmatrix} \begin{pmatrix} \alpha\alpha^* & \frac{1}{2} \alpha\delta^* \\ \frac{1}{2} \alpha\delta^* & \delta\delta^* \end{pmatrix} = \begin{pmatrix} \alpha\alpha^*\alpha\alpha^* + \frac{1}{2} \alpha\delta^* \frac{1}{2} \alpha\delta^* & \frac{1}{2} \alpha\alpha^* \delta\delta^* + \frac{1}{2} \alpha\delta^* \delta\delta^* \\ \frac{1}{2} \alpha\delta^* \alpha\alpha^* + \delta\delta^* \frac{1}{2} \alpha\delta^* & \frac{1}{2} \alpha\delta^* \frac{1}{2} \alpha\delta^* + \delta\delta^* \delta\delta^* \end{pmatrix}$$

$$\begin{aligned} \text{Tr} \rho_A^2 &= \alpha\alpha^*\alpha\alpha^* + \frac{1}{2} \alpha\alpha^* \delta\delta^* + \frac{1}{2} \alpha\delta^* \delta\delta^* + \delta\delta^* \delta\delta^* = \\ &= (\alpha\alpha^*)^2 + \frac{1}{2} \alpha\alpha^* \delta\delta^* + (\delta\delta^*)^2 = \\ &= \underbrace{(\alpha\alpha^* + \delta\delta^*)^2}_{=1} - \frac{3}{2} \alpha\alpha^* \delta\delta^* = \underline{\underline{1 - \frac{3}{2} \alpha\alpha^* \delta\delta^*}} < 1 \text{ kromě když } \alpha=0 \text{ nebo } \delta=0 \\ &\quad \hookrightarrow \text{nejedná se o čistý stav} \end{aligned}$$

⑦  $\langle H_A \rangle_0 = \text{Tr}(\rho_{A,0} H_A)$  ( $t=0$ )

$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{2} \hbar\omega & 0 \\ 0 & -\frac{1}{2} \hbar\omega \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \hbar\omega & 0 \\ 0 & 0 \end{pmatrix} \Rightarrow \text{Tr}(\rho_{A,0} H_A) = \underline{\underline{\frac{1}{2} \hbar\omega}} = \langle H_A \rangle$$

⑧ konečný stav  $\rho_A(t)$

$$\langle H_A \rangle_t = \text{Tr}(\rho_{A,t} H_A) =$$

$$\begin{pmatrix} \alpha\alpha^* & \frac{1}{2} \alpha\delta^* \\ \frac{1}{2} \alpha\delta^* & \delta\delta^* \end{pmatrix} \begin{pmatrix} \frac{1}{2} \hbar\omega & 0 \\ 0 & -\frac{1}{2} \hbar\omega \end{pmatrix} = \begin{pmatrix} \alpha\alpha^* \frac{1}{2} \hbar\omega & -\frac{1}{2} \alpha\delta^* \frac{\hbar\omega}{2} \\ +\frac{1}{2} \alpha\delta^* \frac{1}{2} \hbar\omega & -\frac{1}{2} \delta\delta^* \hbar\omega \end{pmatrix} \Rightarrow \text{Tr}(\rho_{A,t} H_A) = \underline{\underline{\frac{1}{2} \hbar\omega (\alpha\alpha^* - \delta\delta^*)}}$$

$\Rightarrow H_A$  pro popis hustoty