

## Pozitívne Dú #3

$$\textcircled{1} \quad 2 \text{ častic} \rightarrow \text{stan } |+\rangle \rightarrow \text{stan } |+\rangle = \frac{1}{\sqrt{2}}(|+\rangle - i|-\rangle)$$

$$\Rightarrow |+\rangle = |+\rangle \otimes \frac{1}{\sqrt{2}}(|+\rangle - i|-\rangle) \\ = \frac{1}{\sqrt{2}}(|\uparrow\rangle - i|\downarrow\rangle)$$

- Postavte získané stan  $|1,0\rangle$ ?

$$|1,0\rangle = \frac{1}{\sqrt{2}}(|\uparrow\rangle + |\downarrow\rangle)$$

$$\sqrt{2} = \langle 1,0 | \psi \rangle =$$

$$= \frac{1}{\sqrt{2}}(\langle \uparrow\downarrow | + \langle \downarrow\uparrow |) \frac{1}{\sqrt{2}}(|\uparrow\uparrow\rangle - i|\uparrow\downarrow\rangle) =$$

$$= \frac{1}{2} \left( (\langle \uparrow\downarrow | \uparrow\uparrow\rangle - i\langle \uparrow\downarrow | \uparrow\downarrow\rangle) + (\langle \uparrow\downarrow | \uparrow\downarrow\rangle - i\langle \uparrow\downarrow | \uparrow\downarrow\rangle) \right)$$

$$\langle \uparrow\uparrow | \underbrace{\langle \uparrow\downarrow |}_{=0} \underbrace{\uparrow\uparrow}_{=1} \underbrace{-i \langle \uparrow\downarrow |}_{=1} \underbrace{\uparrow\downarrow}_{=1} \underbrace{\langle \uparrow\downarrow | \uparrow\downarrow}_{=0} \underbrace{-i \langle \uparrow\downarrow |}_{=0} \underbrace{\uparrow\downarrow}_{=0}$$

$$= \frac{1}{2} \cdot (0 - i + 0 + 0) = -i \frac{1}{2}$$

$$\Rightarrow P = |\sqrt{2}|^2 = |(-i \frac{1}{2}) + (i \frac{1}{2})|^2 = \underline{\underline{\frac{1}{4}}}$$

- Postavte  $|+1,+\rangle$ ?

$$|+1,+\rangle = |\uparrow\uparrow\rangle$$

$$\sqrt{2} = \langle \uparrow\uparrow | \frac{1}{\sqrt{2}}(|\uparrow\uparrow\rangle - i|\uparrow\downarrow\rangle) = \underline{\underline{\frac{1}{2}}}$$

$$\begin{matrix} 1 & 1 \end{matrix}$$

$$\Rightarrow P = \underline{\underline{2}}$$

- post  $|+1, -1\rangle ?$   
 $|+1, -1\rangle = |\downarrow\downarrow\rangle$   
 $\sqrt{2} = (\downarrow\downarrow | \frac{1}{\sqrt{2}}(|TT\rangle - i|TV\rangle) = 0$   
 $\Rightarrow P = \underline{\underline{0}}$

② • výjádřit  $J^2$  pomocí  $L^2, L_z, L_{\pm}, S^2, S_z, S_{\pm}$

$$J^2 = (\vec{L} + \vec{S})^2 = L^2 + S^2 + 2 \vec{L} \cdot \vec{S}$$

$$\vec{L} \cdot \vec{S} = \frac{1}{2} (L_+ S_- + L_- S_+) + L_2 S_2$$

$$J^2 = L^2 + S^2 + (L_+ S_- + L_- S_+) + 2 L_2 S_2$$

• komutátor  $[J^2, J_z]$

$$\begin{aligned}
 \underline{[J^2, J_z]} &= [L_i L_i + S_i S_i + 2 L_i S_i, L_j + S_j] = \\
 &= \underbrace{[L_i L_i, L_j]}_{[L^2, L_j] = 0} + \underbrace{[S_i S_i, L_j]}_{=0} + 2 \underbrace{[L_i S_i, L_j]}_{S_i [L_i, L_j] = S_i \epsilon_{ijk} L_k} + \\
 &\quad + \underbrace{[S_i S_i, S_j]}_{[S^2, S_j] = 0} + \underbrace{[L_i L_i, S_j]}_{=0} + 2 \underbrace{[L_i S_i, S_j]}_{L_i [S_i, S_j] = L_i \epsilon_{ijk} S_k} = \\
 &= i \epsilon_{ijk} (L_j + S_j) =
 \end{aligned}$$

$$= i \sum_{i,j} \underbrace{(\mathbf{S}_i \cdot \mathbf{L}_j + \mathbf{L}_i \cdot \mathbf{S}_j)}_{\text{S417}} = \underline{\underline{0}}$$