

$10^{40} - 10^{50}$, M1

④ MOTIVACE

Schrödingerova rovnice (1926)

$$\hat{H}\Psi = E\Psi$$

hamiltonian

= operator energie

$$\hat{H} = \frac{\hat{p}^2}{2} - \frac{1}{r}$$

mechanické veličiny
= vlastní hodnoty
energie Ψ = vlnová funkce popisující
volné systématomových
jednotek
(bude použita na přednášce)

v souřadnicové repre (používá se na přednášce)

$$\begin{aligned} \hat{p} &\rightarrow \hat{p} \\ \hat{p}_r &\rightarrow -i\hat{\nabla} \end{aligned}$$

$$\text{pro hamiltonian } \hat{H} = \frac{\hat{p}^2}{2} + V(r)$$

znamená tady

(potenciál závislý pouze na r)
= sférický potenciál

existuje ŠMKO = uplná minima komutujících operátorů

$$\{\hat{H}, \hat{L}^2, \hat{L}_z\}$$

nás hám.

 \hat{L}^2 = operator momentu hybnosti

$$\rightarrow \hat{l}^2 \rightarrow \text{kvadrát } \hat{L}$$

 \hat{L}_z → projekce momentu hybnosti
do směru osy z

$$[\hat{H}, \hat{L}^2] = 0$$

$$[\hat{H}, \hat{L}_z] = 0$$

$$[\hat{L}^2, \hat{L}_z] = 0$$

komutátor dvou operátorů

$$[\hat{A}, \hat{B}] = \hat{A}\hat{B} - \hat{B}\hat{A}$$

~~sférický potenciál~~ → výhodně přejít do sférických souřadnic⇒ můžeme zvolit společnou kvant. vektorskou funkci $\Psi_{nlm}(r)$

$$\hat{H}\Psi_{nlm}(r) = -\frac{1}{2m^2}\Psi_{nlm}$$

$$\hat{L}^2\Psi_{nlm}(r) = l(l+1)\Psi_{nlm}(r) \quad l = 0, 1, \dots, n-1$$

$$\hat{L}_z\Psi_{nlm}(r) = m\Psi_{nlm}(r) \quad m = -l, \dots, l$$

② sférická symetrie → výhodně přejít do sférických souřadnic:

$$x_i = r n_i$$

radialní
sout.

$$x = r \sin\theta \cos\phi$$

$$y = r \sin\theta \sin\phi$$

$$z = r \cos\theta$$

funkčnost
smerový
vektor

(2)

$$x_i = r \cos \varphi$$

$$p_i = -i \frac{\partial}{\partial x_i} = -i \left(\frac{\partial r}{\partial x_i} \frac{\partial}{\partial r} + \frac{\partial \varphi}{\partial x_i} \frac{\partial}{\partial \varphi} + \frac{\partial \theta}{\partial x_i} \frac{\partial}{\partial \theta} \right)$$

$$\begin{aligned} x &= r \sin \theta \cos \varphi \\ y &= r \sin \theta \sin \varphi \\ z &= r \cos \theta \end{aligned}$$

\$\Rightarrow\$ dleme ugyaln \$\vec{r}, \theta, \varphi\$: = 1

$$x^2 + y^2 + z^2 = r^2 \sin^2 \theta \cos^2 \varphi + r^2 \sin^2 \theta \sin^2 \varphi + r^2 \cos^2 \theta = r^2 = 1$$

$$\begin{aligned} r &= \sqrt{x^2 + y^2 + z^2} & x^2 + y^2 &= r^2 \sin^2 \theta (\cos^2 \varphi + \sin^2 \varphi) \\ \theta &= \arctg \frac{\sqrt{x^2 + y^2}}{z} & &= \frac{z^2}{\cos^2 \theta} \sin^2 \theta \\ \varphi &= \arctg \frac{y}{x} & \frac{x}{z} &= \frac{r \sin \theta \cos \varphi}{r \sin \theta \sin \varphi} & \frac{y}{x} &= \frac{\sin \varphi}{\cos \varphi} \end{aligned}$$

$$p_i = -i \left(\frac{\partial r}{\partial x_i} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x_i} \frac{\partial}{\partial \theta} + \frac{\partial \varphi}{\partial x_i} \frac{\partial}{\partial \varphi} \right) = -i \frac{\partial}{\partial x_i}$$

$$\frac{\partial r}{\partial x_i} = \frac{x_i}{r}; \quad \frac{\partial}{\partial x} (x^2 + y^2 + z^2) = \frac{1}{2r} \cdot 2x = \frac{x}{r} = \frac{r \sin \theta \cos \varphi}{r} = \sin \theta \cos \varphi \text{ a. cld.}$$

$$\frac{\partial \theta}{\partial x_i} = \frac{\partial \theta}{\partial x} \left(\arctg \frac{\sqrt{x^2 + y^2}}{z} \right) = \frac{z}{1 + \frac{x^2 + y^2}{z^2}} \cdot \frac{1}{2\sqrt{x^2 + y^2}} \cdot 2x = \frac{z \cdot x}{(x^2 + y^2 + z^2) \cdot \sqrt{x^2 + y^2}} = \frac{r \sin \theta \cos \varphi}{4r^3 \sin^2 \theta} \frac{r \cos \theta - r \sin \theta \sin \varphi}{r^2 \sin \theta} = \frac{1}{r} \cos \theta \cos \varphi$$

$$\frac{\partial \theta}{\partial y} = \frac{\partial \theta}{\partial y} \left(\arctg \frac{\sqrt{x^2 + y^2}}{z} \right) = \frac{z \cdot y}{(x^2 + y^2 + z^2) \sqrt{x^2 + y^2}} = \frac{r \cos \theta \sin \theta \sin \varphi}{r^2 \sin \theta} = \frac{r \cos \theta \sin \varphi}{r}$$

$$\frac{\partial \theta}{\partial z} = \frac{\partial \theta}{\partial z} \left(\arctg \frac{\sqrt{x^2 + y^2}}{z} \right) = \frac{z^2}{z^2} \cdot \frac{1}{\sqrt{x^2 + y^2}} \cdot \frac{-1}{z^2} = \frac{r \sin \theta}{r^2} = \frac{1}{r} \sin \theta$$

$$\frac{\partial \varphi}{\partial x} = \frac{\partial \varphi}{\partial x} \left(\arctg \frac{y}{x} \right) = 1 + \frac{y^2}{x^2} = \frac{1}{x^2 + y^2} = \frac{r \cos^2 \theta \sin^2 \varphi}{r^2 \sin^2 \theta} = \frac{\cos^2 \theta \sin^2 \varphi}{r^2 \sin^2 \theta} = \frac{\cos^2 \theta}{r^2}$$

$$\frac{\partial \varphi}{\partial y} = \frac{\partial \varphi}{\partial y} \left(\arctg \frac{y}{x} \right) = 1 + \frac{y^2}{x^2} \cdot \frac{1}{y^2} = \frac{1}{x^2 + y^2} = \frac{r \cos^2 \theta \sin^2 \varphi + r^2 \cos^2 \theta \sin^2 \theta \sin^2 \varphi}{r^2 \sin^2 \theta} = \frac{\cos^2 \theta \sin^2 \varphi + \cos^2 \theta \sin^4 \theta}{r^2 \sin^2 \theta}$$

$$\frac{\partial \varphi}{\partial z} = 0$$

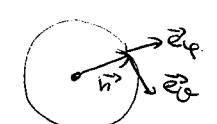
$$\rightarrow \text{then. } p_i = -i \frac{\partial}{\partial x_i} = -i \left(n_i \frac{\partial}{\partial r} + \frac{\nabla^n}{r} \right)$$

$$\frac{\partial}{\partial x_i} = n_i \frac{\partial}{\partial r} + \frac{\nabla^n}{r}$$

$\vec{n} = (\sin \theta \cos \varphi, \sin \theta \sin \varphi, \cos \theta)$ smakový vektor

$\nabla^n = \vec{e}_r \frac{\partial}{\partial r} + \vec{e}_{\varphi} \frac{\partial}{\partial \varphi} + \vec{e}_{\theta} \frac{\partial}{\partial \theta}$ \Rightarrow občajuje všechny 'uhlové' derivace

$$\begin{aligned} \vec{e}_r &= (\cos \theta \cos \varphi, \cos \theta \sin \varphi, -\sin \theta) \\ \vec{e}_{\varphi} &= (-\sin \varphi, \cos \varphi, 0) \end{aligned}$$



\Rightarrow můžou si dát souřadnice

③ $\vec{n} \cdot \nabla^n = 0$

$$\vec{n} = (\sin\varphi \cos\psi, \sin\varphi \sin\psi, \cos\varphi)$$

$$\nabla^n = \underbrace{\hat{e}_r \frac{\partial}{\partial r}}_{=0}, \quad \hat{e}_{\theta} \frac{\partial}{\partial \theta} + \frac{\hat{e}_\varphi}{\sin\varphi} \frac{\partial}{\partial \psi}$$

$$\begin{aligned} \vec{n} \cdot \hat{e}_\theta &= 0 \\ \vec{n} \cdot \hat{e}_\varphi &= 0 \end{aligned} \quad \Rightarrow \quad \underline{\underline{\vec{n} \cdot \nabla^n = 0}}$$

④

$$\hat{e}_\theta = (\cos\varphi \cos\psi, \cos\varphi \sin\psi, -\sin\varphi)$$

$$\hat{e}_\varphi = (-\sin\psi, \cos\psi, 0)$$

④ $\left[\frac{\partial}{\partial x_i}, x_j \right] = \delta_{ij}$

$$\text{obecne: } \left[\frac{\partial}{\partial x}, f(x) \right] = \frac{\partial f}{\partial x} : [A, B] = AB - BA$$

\rightarrow predstavime si jeste jednu fci g, na kt. operatory pustimy.

$$\begin{aligned} \left[\frac{\partial}{\partial x}, f(x) \right] g &= \left(\frac{\partial}{\partial x} (f(x)g) - f(x) \frac{\partial g}{\partial x} \right) g \\ &= \frac{\partial f}{\partial x} g + f(x) \frac{\partial g}{\partial x} - f(x) \frac{\partial g}{\partial x} \\ &= \frac{\partial f}{\partial x} g \quad \Rightarrow \quad \underline{\underline{\left[\frac{\partial}{\partial x}, f(x) \right] = \frac{\partial f}{\partial x}}} \\ \frac{\partial}{\partial x_i} (x_j f) - x_j \frac{\partial}{\partial x_i} f &= \\ &= \underbrace{x_j}_{\delta_{ij}} \frac{\partial f}{\partial x_i} + x_j \underbrace{\frac{\partial f}{\partial x_i}}_{=0} - x_j \frac{\partial f}{\partial x_i} = \delta_{ij} f \\ &\delta_{ij} \end{aligned}$$

⑤ $\left[n_i \frac{\partial}{\partial r} + \frac{\nabla^n}{r}, r n_j \right] = \delta_{ij} \Rightarrow \boxed{\left[\nabla^n, n_j \right] = \delta_{ij} - n_i n_j}$

$$\begin{aligned} \left[n_i \frac{\partial}{\partial r} + \frac{\nabla^n}{r}, r n_j \right] &= \underbrace{\left[n_i \frac{\partial}{\partial r}, r n_j \right]}_{\downarrow} + \underbrace{\left[\frac{\nabla^n}{r}, r n_j \right]}_{= [\nabla^n, n_j]} = n_i n_j + [\nabla^n, n_j] = \delta_{ij} \quad \rightarrow \underline{\underline{\left[\nabla^n, n_j \right] = \delta_{ij} - n_i n_j}} \\ &n_i \frac{\partial}{\partial r} (r n_j f) - r n_j n_i \frac{\partial f}{\partial r} \\ &n_i n_j f + n_i r n_j \frac{\partial f}{\partial r} - r n_j n_i \frac{\partial f}{\partial r} \end{aligned}$$

$$\Rightarrow \boxed{\left[\nabla^n, n_i \right] = \delta_{ii} - n_i n_i = 3 - 1 = 2}$$

$$\Rightarrow \boxed{= \nabla^n (n_i f) - n_i \nabla^n f = \nabla^n n_i = 2}$$

$$\rightarrow \vec{L} = \vec{r} \times \vec{p}$$

⑥ zavedeme moment hybnosti: (jako v 'klasické' mechanice a estetizujeme)

$$\hat{L}_i = \sum_{j,k} \hat{x}_{jk} \hat{p}_k \rightarrow L_i = \sum_{j,k} \sum_{j,k} x_{jk} \frac{\partial}{\partial x_k}$$

$\hat{x}_j \rightarrow x_j$
 $\hat{p}_k \rightarrow m_k \frac{\partial}{\partial x_k}$

$$\begin{aligned} L_i &= \sum_{j,k} x_{jk} p_k \rightarrow -i \sum_{j,k} x_{jk} \frac{\partial}{\partial x_k} \\ &= -i \sum_{j,k} m_k n_j \left(n_k \frac{\partial f}{\partial r} + \frac{\nabla^n}{r} \right) \\ &= -i \sum_{j,k} m_k n_j \frac{\partial f}{\partial r} - i \sum_{j,k} m_k n_j \frac{\nabla^n}{r} \\ &\quad A \cdot S \\ &= \underline{\underline{-i \sum_{j,k} m_k n_j \nabla^n}} \end{aligned}$$

! pouze uhlodna zavislost, radikalni ne!

(4)

$$\textcircled{7} \quad [\hat{L}_i, \hat{L}_j] = i \varepsilon_{ijk} \hat{L}_k \quad \text{cosz plane } \Rightarrow [P_i, x_j] = -i \delta_{ij} \quad \hat{L}_i = \varepsilon_{ijk} x_j P_k$$

$$[\hat{L}_i, \hat{L}_j] = \cancel{i \varepsilon_{ijk} x_j P_k} \quad [i \varepsilon_{ipq} x_p P_q, i \varepsilon_{jlm} x_m P_l] =$$

$$= + \varepsilon_{ipq} \varepsilon_{jlm} [x_p x_m P_l] =$$

$$* \quad [AB, C] = A[B, C] + [A, C]B \quad \leftarrow \text{distributive rule}$$

$$= + \varepsilon_{ipq} \varepsilon_{jlm} \{ x_p [x_m P_l] + [x_p x_m P_l] P_q \}$$

$$[P_q, P_l] = 0 \quad [x_p, x_m] = 0$$

$$= + \varepsilon_{ipq} \varepsilon_{jlm} \{ x_p \underbrace{[x_m P_l]}_{=i \delta_{qm}} + x_m \underbrace{[x_p P_l]}_{=i \delta_{pn}} \}$$

$$= + i (\varepsilon_{ipm} \varepsilon_{jlm} x_p x_m + \varepsilon_{ipq} \varepsilon_{jlm} x_m x_p)$$

$$= \varepsilon_{im} \varepsilon_{mj} \quad = \varepsilon_{ppi} \varepsilon_{pjn}$$

$$= \delta_{im} \delta_{jn} - \delta_{ij} \delta_{pn} \quad = \delta_{qj} \delta_{im} - \delta_{ij} \delta_{qm}$$

$$= -i (x_j p_i - \cancel{\delta_{ij} x_p p_j} - x_i p_j + \cancel{\delta_{ij} x_q p_q})$$

polite scittaci indecy $\rightarrow q=p$

$$= +i (x_i p_j - x_j p_i)$$

etc.

$$i \varepsilon_{ijk} L_k = i \varepsilon_{ijk} \sum_{lmn} x_m P_l = i \varepsilon_{ijk} \sum_{lmn} x_m P_m =$$

$$= i (\delta_{im} \delta_{jn} - \delta_{ij} \delta_{jm}) x_m P_m$$

$$= i (x_i P_j - x_j P_i)$$

$$\Rightarrow [\hat{L}_i, \hat{L}_j] = i \varepsilon_{ijk} \hat{L}_k$$

(8) $[\hat{L}_i, \hat{L}_j] = i \varepsilon_{ijk} \hat{L}_k \Rightarrow [\hat{L}_k, \hat{L}^2] = 0$ \hat{L}^2 komutuje s lib. slozence L^2

$$[\hat{L}_k, \hat{L}^2] = [\hat{L}_k, L_m L_m] = L_m [\hat{L}_k, L_m] + [\hat{L}_k, L_m] L_m =$$

↓

$$[ABC] = B[A,C] + [A,B]C$$

$$= L_m i \varepsilon_{kmn} L_n + i \varepsilon_{kmn} L_n L_m$$

$$= i \varepsilon_{kmn} (\underbrace{L_m L_n + L_n L_m}_{\begin{matrix} \uparrow \\ A \\ m \leftrightarrow n \end{matrix} \quad \begin{matrix} \downarrow \\ S \\ m \leftrightarrow n \end{matrix}}) = 0$$

$$\begin{aligned}
 9) \quad \nabla^2 &= \frac{\partial^2}{\partial x_i \partial x_i} = (h_i \frac{\partial}{\partial r} + \frac{\nabla^n}{r})(h_i \frac{\partial}{\partial r} + \frac{\nabla^n}{r}) = \quad (5) \\
 &= h_i \frac{\partial}{\partial r} (h_i \frac{\partial}{\partial r}) + h_i \frac{\partial}{\partial r} \left(\frac{\nabla^n}{r} \right) + \frac{\nabla^n}{r} h_i \frac{\partial}{\partial r} + \frac{\nabla^n}{r} \cdot \frac{\nabla^n}{r} \\
 &\quad \underbrace{h_i h_i}_{=1} \frac{\partial^2}{\partial r^2} + h_i \frac{\partial}{\partial r} \left(\frac{-1}{r^2} + \frac{1}{r} \frac{\partial}{\partial r} \right) + \frac{\nabla^n}{r} \frac{1}{r} \frac{\partial}{\partial r} = \frac{1}{r^2} (\nabla^n)^2 \\
 &\quad = 0 \quad (\text{vzádlość}) \quad = 2 \quad (\text{vzádlość}) \\
 &= \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} + \frac{(\nabla^n)^2}{r^2} \\
 \boxed{\nabla^2 = \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} + \frac{(\nabla^n)^2}{r^2}}
 \end{aligned}$$

$$\begin{aligned}
 L^2 &= L_i L_i = \cancel{\sum_{ijkP} \epsilon_{ijk} X_j P_k \epsilon_{ipq} X_p P_q} \\
 &\quad \cancel{\sum_{ijkP} \epsilon_{ijk} h_j \nabla^n \epsilon_{ipq} h_p \nabla^n q} \\
 &\quad = \cancel{\sum_{ijkP} (\delta_{jk} \delta_{in} - \delta_{jn} \delta_{ik}) h_j \nabla^n h_p \nabla^n q} \\
 &\quad = L_i = \sum_{ijkP} \epsilon_{ijk} X_j P_k = \dots = -i \sum_{ijkP} h_j \nabla^n i \quad (\text{vzádloží jsme dali}) \\
 &= (-i) \sum_{ijkP} h_j \nabla^n i \quad (-i) \sum_{ijkP} h_p \nabla^n q \\
 &= - (\delta_{jp} \delta_{kq} - \delta_{jq} \delta_{kp}) h_j \nabla^n h_p \nabla^n q \\
 &= - (h_p \nabla^n h_p \nabla^n q - h_q \nabla^n h_p \nabla^n q) \\
 &= \cancel{h_p \nabla^n h_p \nabla^n q} + \cancel{\delta_{qp} - h_q h_p} \\
 &\quad \cancel{[h_q, h_p]} = \nabla^n h_p - h_p \nabla^n q = \delta_{qp} - h_q h_p \\
 &= - [h_p (i_p \nabla^n q + \delta_{qp} - h_q h_p) \nabla^n q - 2 \cancel{h_q \nabla^n q}] \\
 &= - \cancel{h_p h_p \nabla^n \nabla^n q} - \cancel{h_p \nabla^n q} + \cancel{h_p h_q h_p \nabla^n q} \\
 &= - D_q^n D_q^n = - (\nabla^n)^2 \\
 \Rightarrow \boxed{L^2 = - (\nabla^n)^2}
 \end{aligned}$$

10) vrátnime se zpět k našemu hamiltoniánku
se sferickým potenciálem

$$\begin{aligned}
 \hat{H} &= \frac{\hat{p}_x^2}{2} + V(r) = \frac{-\nabla^2}{2} + V(r) = -\frac{1}{2} \left(\frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} + \frac{(\nabla^n)^2}{r^2} \right) + V(r) \\
 \hat{p}_x &\rightarrow -i \hbar \frac{\partial}{\partial x_i} \quad \hat{x}_i \rightarrow x_i \\
 &= -\frac{1}{2} \left(\frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} - \frac{L^2}{r^2} \right) + V(r)
 \end{aligned}$$

$\{H, L^2, L\}$ GJKO:

$$\begin{aligned}
 [L_i, \hat{p}_j] &= 0 \quad \text{jste v\v{e}k v\v{e}k} \\
 [H, L^2] &= 0 \quad \} \quad \text{v\v{e}k v\v{e}k (protože)} \\
 [L_i, H] &= 0
 \end{aligned}$$

(6)

1) Zavedeme radikální hybnost $p_r = -i(\frac{\partial}{\partial r} + \frac{1}{r})$

$$\Rightarrow p_r^2 = -i(\frac{\partial^2}{\partial r^2} + \frac{1}{r^2}) \Leftrightarrow (\frac{\partial^2}{\partial r^2} + \frac{1}{r^2})$$

$$= -(\frac{\partial^2}{\partial r^2} - \frac{1}{r^2} + \frac{1}{r^2} \frac{\partial^2}{\partial r^2} + \frac{1}{r^2} \frac{\partial^2}{\partial r^2} + \frac{1}{r^2})$$

$$= -(\frac{\partial^2}{\partial r^2} + \frac{2}{r^2} \frac{\partial^2}{\partial r^2})$$

$$\Rightarrow \vec{p} \cdot \vec{p} = -\left(\frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial^2}{\partial r^2} + \frac{(Dn)^2}{r^2}\right)$$

$$= p_r^2 + \frac{L^2}{r^2}$$

$$\Rightarrow H = \frac{\vec{p} \cdot \vec{p}}{2} + V(r) = \frac{p_r^2}{2} + \frac{L^2}{2r^2} + V(r)$$

až sem mohou určitě dojet

2) $H = \frac{p_r^2}{2} + \frac{L^2}{2r^2} + V(r)$

$H\Psi = E\Psi$

$$\left(\frac{p_r^2}{2} + \frac{L^2}{2r^2} + V(r)\right) \Psi_{n,l,m} = E_{n,l} \Psi_{n,l,m}$$

protože máme ŠMKO
 $\uparrow \quad \{H, L^2, L_z\}$

vlh. fórmu můžeme charakterizovat 3 QM (jde o vše na středu...)

- * energie obecně závisí na n a l
 * na n nezávisí, protože n se nevystýká je \sqrt{H}
 * speciálně pro coulombovský potenciál $V(r) \propto -\frac{1}{r}$
 (číjen pro vej)

energie závisí pouze na l

(stačí trochu jiný potenciál - i třeba jen relativistické korekce - a energie už závisí na l)

$$H\Psi_{n,l,m} = E_{n,l} \Psi_{n,l,m}$$

$$L^2 \Psi_{n,l,m} = l(l+1) \Psi_{n,l,m}$$

$$L_z \Psi_{n,l,m} = m \Psi_{n,l,m}$$

$$\Rightarrow \left(\frac{p_r^2}{2} + \frac{l(l+1)}{2r^2} + V(r)\right) \Psi_{n,l,m}(r, \theta, \varphi) = E_{n,l} \Psi_{n,l,m}(r, \theta, \varphi)$$

vhodné fórmu separovat: $\Psi_{n,l,m}(r, \theta, \varphi) = R_{n,l}(r) Y_{lm}(\theta, \varphi)$

radikální část vlnová část
 $\uparrow \qquad \uparrow$
 \Rightarrow spherical harmonicity

$$\left[\frac{p_r^2}{2} + \frac{l(l+1)}{2r^2} + V(r)\right] R_{n,l} = E_{n,l} R_{n,l}$$

$$L^2 \Psi_{lm} = l(l+1) \Psi_{lm}$$

$$L_z \Psi_{lm} = m \Psi_{lm}$$

konec první části na stránku -

polekud zbyde cas:

(7)

$$(13) [L_i, h_j] = i \epsilon_{ijk} h_k$$

$$[L_i, h_j] = [i \epsilon_{ijk} h_p D_q^h, h_j] = -i \epsilon_{ipq} [h_p D_q^h, h_j] = -i \epsilon_{ipq} h_p [D_q^h, h_j].$$

$$\delta_{qj} - h_q h_j$$

$$= -i \epsilon_{ipq} h_p \delta_{qj} + i \epsilon_{ipq} h_p h_j$$

\downarrow
 $p > q, p < q$
A S $\Rightarrow 0$

$$= -i \epsilon_{ipj} h_p$$

$$= i \epsilon_{ijp} h_p \quad \epsilon_{ipj} = -\epsilon_{ijp}$$

$$(14) [L_z^2, h_j] = -2(D_j^h)^2$$

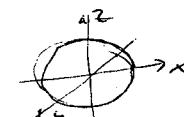
$$[L_z^2, h_j] = [-(D_x^h)^2, h_j] = [-D_x^h D_z^h, h_j] = -D_z^h [\underbrace{D_x^h h_j}_{} - \underbrace{D_x^h h_j}_{} D_x^h] =$$

$\#$

$$= \delta_{xj} h_x h_j - \delta_{zj} h_z h_j$$

$$= -D_x^h + D_x^h h_z h_j - D_x^h + \underbrace{h_z h_j D_x^h}_{=0}$$

$$= -2(D_x^h h_j)$$



s-orbital - tak, jak ho známe ze středoškolské chemie

určitne je normalizace

$$\int |Y_{00}|^2 d\Omega = 1$$

$$\int |Y_{00}|^2 \int \sin \theta d\theta d\phi \int d\phi = |Y_{00}|^2 \cdot 2\pi \cdot 2\pi = 4\pi |Y_{00}|^2 = 1$$

$$l=1 m_l = -1, 0, 1$$

$$l=2 m_l = -2, -1, 0, 1, 2$$

$$\frac{1}{\sqrt{4\pi}}$$

\rightarrow a všechny, že $|Y_{00}|^2$ můžeme nějak vysvětlit
dokl. orbitaly (P_1, \dots)

\hookrightarrow použijeme k tomu komutátor $[L_z^2, h_j] = 2(h_j - D_j^h) Y_{00}$ ← operátory jsou rovnací, musí platit, i když zapísané na různých místech

$$[L_z^2 h_j] Y_{00} = 2(h_j - D_j^h) Y_{00}$$

$$(L_z^2 h_j - h_j L_z^2) Y_{00} = 2(h_j - D_j^h) Y_{00}$$

$\Rightarrow 0 \quad \Rightarrow 0$ (protože h_j je základní funkce, která má všechny základní funkce vlastnosti)

$$L_z^2 h_j Y_{00} = 2 h_j Y_{00} = 1(l+1) h_j Y_{00}$$

nové funkce s $l=1 \rightarrow j=x,y,z \Rightarrow P_x, P_y, P_z$ orbitalky (všechny funkce L_z plní vlastnost L_z)

a podobné můžeme získat dle orbitály:
 započítáme z houze komutátorem $[L^2, h_j]$:

$$[L^2, h_j] n_{\pm} \Psi_0 = 2(h_j - \delta_{jj}^n) n_{\pm} \Psi_0 \quad \rightarrow \quad n_{\pm} D_j^n + \delta_{jj}^n - n_{\pm} h_j$$

$$(L^2 h_j - h_j L^2) n_{\pm} \Psi_0 = 2h_j n_{\pm} \Psi_0 - 2D_j^n h_j \Psi_0 \quad \rightarrow \quad D_j^n \Psi_0 = 0$$

$$\Rightarrow 0$$

$$L^2 h_j n_{\pm} \Psi_0 - 2h_j n_{\pm} \Psi_0 = 2h_j h_{\pm} \Psi_0 - 2(\delta_{jj}^n - n_{\pm} h_j) \Psi_0 \quad + \cancel{\frac{1}{3} \delta_{jj}^n \Psi_0}$$

$$L^2(n_j n_{\pm} - \frac{1}{3} \delta_{jj}^n) \Psi_0 = 6(n_j n_{\pm} - \frac{1}{3} \delta_{jj}^n) \Psi_0$$

↑
toto ještě musíme prokázat, že $L^2 \delta_{jj}^n \Psi_0 = \delta_{jj}^n L^2 \Psi_0 = \delta_{jj}^n 0 = 0$

$$6 = 2(2+l) \rightarrow \underline{(n_j n_{\pm} - \frac{1}{3} \delta_{jj}^n) \Psi_0} \quad \text{jste u v. f. } l^2 \text{ s } l=2$$

\Leftarrow oborbitály
(opět dle v. f. l_2)

Vlastní funkce l_2 můžeme dostat podobně:

$$(16) \quad R = (\sin\theta \cos\varphi, \sin\theta \sin\varphi, \cos\theta)$$

Započítáme shodování a rozdílovací operátory (ladder operators)

$$n_{\pm} = n_x \pm i n_y = \sin\theta \cos\varphi \pm i \sin\theta \sin\varphi$$

$$= \sin\theta (\cos\varphi \pm i \sin\varphi)$$

$$= \sin\theta e^{\pm i \varphi}$$

$$n_z = \cos\theta$$

$$[L_i, n_j] = i \epsilon_{ijk} h_k \Rightarrow [L_z, n_x] = 0$$

(viz dále)

$$\bullet \quad [L_z, n_{\pm}] = [L_z, n_x \pm i n_y] = [L_z, n_x] \pm i [L_z, n_y]$$

$$= i \epsilon_{zxy} n_y \pm i(-i \epsilon_{zyx}) n_x$$

$$\stackrel{+1}{\Leftarrow} \stackrel{-1}{\rightarrow}$$

$$= \pm(n_x \pm i n_y) = \underline{\pm n_{\pm}}$$

a opět proapočítáme op. souhlasná Ψ_0 :

$$[L_z, n_x] \Psi_0 = 0 \quad [L_z, n_{\pm}] \Psi_0 = \pm n_{\pm} \Psi_0$$

$$L_z n_x \Psi_0 = 0$$

$$(L_z n_{\pm} \Rightarrow n_{\pm} L_z) \Psi_0 = \pm n_{\pm} \Psi_0$$

$$\stackrel{+1}{\Rightarrow} \stackrel{-1}{\rightarrow}$$

$$L_z(n_{\pm} \Psi_0) = \pm(n_{\pm} \Psi_0)$$

$$\Rightarrow \Psi_0 \propto \Psi_0$$

$$\Psi_{1,\pm 1} \propto n_{\pm} \Psi_0$$

α je konst. \rightarrow a normalizace $\int d\Omega |\Psi_{l,m}|^2 = 1$

$$\Rightarrow \Psi_{1,0} = \sqrt{\frac{3}{4\pi}} n_2 = \sqrt{\frac{3}{4\pi}} \cos\theta$$

$$\Psi_{1,\pm 1} = (\pm) \sqrt{\frac{3}{8\pi}} \sin\theta e^{\pm i \varphi}$$